

## December 4:

### 13:00 – 14:00 Registration

Venue: Faculty of Mechanical Engineering, Brno University of Technology

Technická 2896/2, Brno, Czech Republic

### 14:00 Opening ceremony

### 14:20 – 15:45 Section Avionics

time	ID	Authors	Title
		Plenary lecture	
14:15	-	Luděk Janák, Sr Systems Engineering Supervisor, Honeywell Aerospace Technologies, Flight Systems COE	Development and Certification of Mechatronic Systems for Aircraft Applications: A Crash Course
14:45		Opportunity for mechatronics - Introduction of Horizon Europe BAANG project: Building Actions in Smart Aviation with Environmental Gains	
15:00	100	Jan Bajer, Miroslav Hrstka, Zahra Sharif Khodaei, M.H. Aliabadi, Zdenek Hadas	Geometry Optimization of a Highly Flexible Gradient Metamaterial Structure Using a Differential Evolution Algorithm
15:15	75	Vojtěch Zůbek, Jakub Hnidka	Simplified 6DoF Flight Model of the Missile
15:30	63	Vadim Starý, Václav Křivánek	Integrating Mechatronics Principles in Modern Air Defence Systems

### 15:45 – 16:30 Coffee break

### 16:30 – 18:00 Section Modelling

time	ID	Authors	Title
16:30	90	Denys Zaikin	Comparison of Three-Winding Transformer Model Extraction Using FEMM and COMSOL Multiphysics®
16:45	46	Muhammad Imran Khan, Badr M. Alshammari	Modeling Quantum Ballistic Transport and Quantum Confinement of Carriers in Advanced 3D FinFET
17:00	43	Daniel Klíč, Martin Minarčík, Aleš Polzer, Jiří Tůma, Jiří Marek, Michal Holub	Digital twin for CNC machine tools design
17:15	19	Matija Hoić, Nenad Kranjčević, Dominik Birt	Design of an active seat suspension based on the Kempe mechanism
17:30	80	Vladimir Skrivanek, Ondrej Rubes, Zdenek Hadas	Modal Properties Tuning Analysis of Dynamic System with Piezoelectric Components
17:45	71	David Grasev, Adolf Jílek	A Novel Approach to Modeling of Compressor Characteristics

**18:00 – 19:30 Posters & Welcome Drink**

ID	Authors	Title
14	Igor Halenar, Bohuslava Juhasova, Martin Juhas, Lenka Halenarova	Design of a Smart Condition Monitoring System of Equipment in the Production Process
15	Lenka Halenarova, Pavol Tanuska, Bohuslava Juhasova, Martin Juhas, Igor Halenar	Design of a Data Collection Layer for Complementary Diagnostic and Condition Monitoring System of a Robotic Workplace
16	Chi Chen, Kuo-Shen Chen, Stanislav Vechet, Yu-Jun Kuo	An Integrated LCD Quality Assessment Flow based on the Integration of Image Processing, Ergonomics, and Machine Learning
21	Ľubica Miková, Erik Prada, Michal Kelemen, Ivan Virgala	Modelling a non-holonomic mechatronic system based on the bicycle chassis principle
23	Martin Juhás, Bohuslava Juhásová, Igor Halenár, Milan Daňo, Lenka Halenárová, Fedor Burčiar	StateFlow as a Tool of the Hybrid X-in-the-Loop Technique in the Model-Based Design Approach to the Control Systems Design in Industrial Automation
25	Fedor Burčiar, Martin Juhás, Bohuslava Juhásová, Pavel Važan, Igor Halenár, Lenka Halenárová	Automated Production Data Integration and Processing via Simulation Based Digital Twin
30	Akeel Othman, Dušan Maga, Jaromír Hrad	Energy-Aware Adaptive QoS Algorithm for IoT
40	Jean Motsch, Yves Bergeon, Vaclav Krivanek	Optimization of Hyperspectral Image Classification Using Monte Carlo-Based Band Reduction
47	Darina Hroncová, Patrik Šarga, Erik Prada, Ľubica Miková	Complete kinematic analysis of the joint variables of the robot mechanism during the end-effector's movement along a circular path
49	Joanna Bijak, Grazia Lo Sciuto, Zygmunt Kowalik, Tomasz Trawiński	2D Finite Element modeling and analysis of single-turn coil configuration in magnetic spring energy harvester
51	Lukáš Sobotka, Aleš Palkovič, Jiří Teichman, Roman Pechánek	Parametric optimization of the cooling ducts of the PMSM
52	Jan Laksar, Martin Bělík, Karel Hruška	Additional Losses in the Winding under Higher Frequency Current
55	Ondrej Majercak, Jaroslav Romancik, Marek Vagas	IoT approach implementation based on flexible and robust Node-RED platform for workplace digitisation increasing
59	Pawet Dymora, Mirosław Mazurek, Maciej Szuberla	Implementation of artificial intelligence in Internet search
60	Pawet Dymora, Mirosław Mazurek, Jakub Adamek	Applying artificial intelligence methods to identify selected cybersecurity problems in computer networks
61	Shreyan Banerjee, Aasifa Rounak, Vikram Pakrashi	Adaptive Linear Control of a Cartpole using Minimum Spiking Neurons trained with Prescribed Error Sensitivity
64	Josef Casar, Vilem Hanus, Pavel Rehak	Sensors Combinations as a Key for Effective Air Defence
65	Erika Sujová, Daniela Vysloužilová, Vanessa Prajová, Alžbeta Klimentová	Optimization of the Aluminium Waste Sorting Process by Using Simulation Models
69	Stanislav Vechet, Jiri Krejsa, Kuo-Shen Chen	Vertical Stabilization of Bipedal Walking Drone PAVO with Proximal Policy Optimization
70	Petar Gljušićić, Marko Perčić, Saša Zelenika	Autonomous Energy Harvesting – based System for Honeybee Hive Monitoring

88	Daniel Ferreira, Armando Cordeiro, Luís Rocha, J. Fernando Silva, E. Romero Cadaval, C. Roncero Clemente, Daniel Foito, João F. Martins, V. Fernão Pires	Seven-Level Transformerless Inverter with a Double Boost Controlled Cell
89	Tomasz Haniszewski, Jerzy Margielewicz, Sławomir Bucki, Damian Gąska	The influence of approximating the mechanical characteristics of a hyperelastic vibration amplifier on its dynamic properties
93	Robert Rakay, Marek Vagas	Usage and added value of IO-Link platform in the context of Industry 4.0
98	Jerzy Margielewicz, Damian Gąska, Tomasz Haniszewski, Sławomir Bucki	Selected tools for the analysis of energy harvesters nonlinear dynamics

### Poster Preparation Instructions

1. The maximum poster size is ISO standard A0 size, 84cm wide x 119cm (33in x 47in).
2. There is no template for posters. However your poster should include:
  - The paper title and all authors at the top of the poster
  - A brief introduction, goals, experimental detail, conclusions, and references; presented in a logical and clear sequence
  - Explanations for each graph, picture, and table
3. Use easily read type. Suggested minimum font sizes:
  - Title: 36-point type
  - List of authors: 25-point type
  - Body copy should be double-spaced text: 15-point type
4. Make the poster as clear as possible, limit the text, and give preference to graphs and schemes.
5. Put the poster up on the board with the corresponding number on December 4 before 5 pm. Supplies for attaching the poster will be available.
6. The most successful posters are graphically rich presentations of your research that highlight and summarize the main points, with the poster presenter filling in the details in person at the session

## December 5:

### 09:00 – 10:30 Sections Mechatronics I

time	ID	Authors	Title
9:00	56	Suliman Badour, Martin Novák	Real-Time Vision-Based Fault Detection System for FDM 3D Printing Using Convolutional Neural Networks
9:15	38	Luca Andrea Mifsud, Kenneth Scerri, Mario Farrugia	Regression Analysis of Factors Affecting Round-Trip Regenerative Braking Efficiency using Real-World Data
9:30	99	Radek Musil, Radim Farana, Robert Rouš, Šimon Bilík	Fuzzy controller tuning methods for typical plant types
9:45	37	Luca Andrea Mifsud, Thor Scicluna, Kenneth Scerri, Mario Farrugia	Experimental Investigation of Downhill Regenerative Braking of Electric Vehicles from CAN Bus Data
10:00	62	Juraj Ďuďák, Daniel Gurín, Matúš Nečas	Design of a device for automatic evaluation of the level of individual perception of sensory stimuli
10:15	96	Huseyin Fatih SEN, Yavuz Selim TASPINAR	Body Performance Analysis with Machine Learning and ANOVA Methods

### 10:30 – 11:00 Coffee break

### 11:00 – 12:30 Section Electrical Devices and Machines

time	ID	Authors	Title
11:00	35	Kusuma Priya Krovi, Jan Bauer	Control Strategy of Buck and Boost Converters using MATLAB Software
11:15	101	Petr Sosna, Zdenek Hadas	Power Optimization of Hybrid Energy Harvesting from Mechanical Vibrations Using Piezoelectric and Electromagnetic Mechanisms
11:30	50	Karel Hruska, Lukas Sobotka, Zdenek Frank, Jan Laksar	Optimal Parameters Choice for Synchronous Reluctance Machines
11:45	66	Patrik Kalaj, Radek Čermák	Iron loss in multiphase machines
12:00	91	Hikaru Suzuki, Katsuhiko Hirata, Noboru Niguchi	Torque Improvement Method for Flux Modulated Motor by Inserting Magnets between Pole Pieces
12:15	92	Kaito Hori, Katsuhiko Hirata, Noboru Niguchi	Bearingless Magnetic-Geared Motor Achieving Both Stable Magnetic Levitation and High Torque

### 12:30 – 13:30 Lunch

**13:30 – 14:45 Section Measurement**

time	ID	Authors	Title
13:30	77	Marek Nowakowski	Operational environment impact on sensor capabilities in special purpose Unmanned Ground Vehicles
13:45	102	Alena Hajkova, Milos Hammer	Application of Modern Approaches to Solving Diagnostic Tasks in Industry
14:00	44	Andrej Potanko, Adam Jelínek, Tomáš Marek, Aleš Polzer, Libor Žák, Michal Holub	Case study of the influence of linearity uncertainty on the applicability and capability of CNC machine tools
14:15	45	Mikuláš Szabari, Jan Berhold, Jan, Vetiška, František Bradáč, Michal Holub, Martin Dix	Case study of Robot Machining at different working space locations
14:30	13	Denis Benka, Gabriel Gaspar, Roman Budjac, Rastislav Elias, Martin Skovajsa	Design and Implementation of the Grouting Process Measurement Device with a Datalogger

**14:45 – 15:15 Coffee break****15:15 – 16:15 Section Robots**

time	ID	Authors	Title
15:15	74	Ramy ElMallah, Nima Zamani, Chi-Guhn Lee	Human 0, MLLM 1: Unlocking New Layers of Automation in Language-Conditioned Robotics with Multimodal LLMs
15:30	94	Soňa Michalková, Kryštof Wojnarowský, Šimon Kolenyák, Matěj Kantor, Jakub Arm	Design a Coffee-making Process Unit using Virtual Twin and Virtual Commissioning
15:45	54	Ondrej Vanicek, Michal Chalus, Jindrich Liska	Coverage Path Planning for Robotic Laser Surfacing Applications Based on 3D Scanning
16:00	57	Suliman Badour, Martin Novák	Kinematic Analysis and Torque Dynamics of a 5-DOF Robotic Manipulator for Enhanced Precision and Fault Detection in FDM 3D Printing

**18:30 Concert – Folk band Okybača****19:00 conference dinner**

## December 6:

### 09:00 – 10:30 Section Measurement and Monitoring

time	ID	Authors	Title
9:00	27	Lukáš Zdražil, Zdeněk Roubal	Electrical Properties Measurement of Building Materials
9:15	39	Thor Scicluna, Mario Farrugia	Experimental Investigation of an AdBlue® Injection System and Implementation on a Dual-Fuel (Diesel/LPG) Engine
9:30	68	Pavel Krýsl, Martin Jára	Design of current measurement circuit using PCB Rogowski coils for resonant converters
9:45	73	Jan Hejda, Patrik Kutilek, Petr Volf, Marek Sokol, Lydie Leova, Jan Tonner, Markéta Hejsková, Veronika Kotolová, Miroslav Rozložnik, Tommy Sugiarto, Yi-Jia Lin, Kun-Lun Huang, Wei-Chun Hsu	Wearable System for Monitoring the Physical Conditions in Isolated, Confined and Extreme Environments
10:00	86	Diogo Marciano, Mafalda Seixas, Rita Pereira, Armando Cordeiro, Rui Guerreiro, José G. Lopes, V. Fernão Pires, Daniel Foito, Sónia F. Pinto	Improving Safety Roads with LoRa Communication Devices: Features and Limitations
10:15	82	Jeong-Tae Kim, Quoc-Bao Ta, Ngoc-Lan Pham	Integrated monitoring of stress and damage using CNN deep learning of electromechanical impedance responses of CSA sensor

### 10:30 – 11:00 Coffee break

### 11:00 – 12:30 Section Mechatronics II

time	ID	Authors	Title
11:00	79	Snajder Jan, Krejsa Jiri	Automation-Driven Dataset Preparation for Continuous Czech Sign Language Recognition
11:15	26	Daniel Stümke, Simon Peter, Daniel Görges	Ellipse Fitting With a Dual Kalman Filter for an Adaptive Angle Tracking Observer
11:30	97	Denis Benka, Gabriel Gaspar, Veronika Nemlahova, Eduard Nemlaha, Roman Budjac	Proposal of a Remote-Control System for Building Lighting Management
11:45	76	Mario Hirz, Christian Flechl, Nathanael Schachner, Alexander Pommer	Novel concept for automated charging of professional electric vehicle fleets
<b>Plenary lecture</b>			
12:00	10	Jui-Chien Tu, Yun-luang Wang, Jia-Chang Wang, Filip Ksica, Zdenek Hadas	Development of Integrated 3D Printing and Automated Embedding System

### 12:30 Closing ceremony

### 13:00 lunch